1-4-2019

Jail

Obtener la matriz T

Cinemática de Robots

Jesús Jail Avalos Lupercio.

Ing. Mecatrónica 8º A

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| Eslabón |  |  | d |  |
| 1 | 0 | -90 |  |  |
| 2 | 0 | 90 | 0 |  |
| 3 | 0 | 0 |  |  |



